

1. Introduction and Motivation

acoustic mechanism of flue instruments is not understood completely

feedback mechanism between the air-jet and a resonance tube

direct aeroacoustic simulation using compressible flow solver [1]

huge computational cost (high-resolution mesh & small time steps)

(finite-difference) lattice Boltzmann method [2]

high effective performance on low b/f machines [3]

	Order of Accuracy	Calculation Mesh
LBM	second-order	uniform cartesian mesh
FDLBM	arbitrary-order	generalized coordinate system

Arithmetic Intensity

LBM FDLBM(low-order) FDLBM(high-order)

2. Numerical Methods and Implementation

[LBM]

discrete BGK equation

$$\frac{\partial f_i}{\partial t} + c_i \frac{\partial f_i}{\partial \mathbf{x}} = -\frac{1}{\tau} [f_i - f_i^{(0)}]$$

first-order upwind
first-order euler

$$\frac{|c_i| \Delta t}{\Delta x} = 1$$

lattice Boltzmann equation

$$f_i(t + \Delta t, \mathbf{x} + \mathbf{c}_i \Delta t) = f_i(t, \mathbf{x}) - \frac{1}{\tau} [f_i(t, \mathbf{x}) - f_i^{(0)}(t, \mathbf{x})]$$

[FDLBM]

$$\frac{\partial f_i}{\partial t} + c_i \frac{\partial f_i}{\partial \mathbf{x}} - \frac{Ac_i}{\tau} \frac{\partial (f_i - f_i^{(0)})}{\partial \mathbf{x}} = -\frac{1}{\tau} [f_i - f_i^{(0)}]$$

third-order upwind (UTOPIA)

$$c_x \frac{f}{\partial x} = c_x \frac{f(x-2\Delta x) - 8f(x-\Delta x) + 8f(x+\Delta x) - f(x+2\Delta x)}{12\Delta x} + |c_x| \frac{f(x-2\Delta x) - 4f(x-\Delta x) + 6f(x) - 4f(x+\Delta x) + f(x+2\Delta x)}{12\Delta x}$$

D209 Model

Discrete velocity vectors

i	Discrete velocity vectors	c
0	(0,0)	0
1~4	(1,0),(0,1),(-1,0),(0,-1)	1
5~8	(1,1),(-1,1),(-1,-1),(1,-1)	√2

Shared Memory

different load position for FD schemes

fluid node
halo node

2-step loading

avoid warp divergence

CPU flowchart: start -> initialize data -> execution kernels -> export time step -> export data -> end condition -> end

GPU flowchart: start kernels -> calculate equilibrium function -> calculate boundary condition -> calculate collision term -> calculate advection term -> end kernels

Coalesced Access

```
for (int k = 0; k < kDirectionNum; k++)
  [i + j * x_cell_num_ + k * x_cell_num_ * y_cell_num_]
  template Kernel + Concurrent Stream
  template<typename T, int k>
  ...global... void update(const T *dfp, const T *ledf, T *df);
  update<T, k> <<<grid, block, 0, stream[k]>>>(dfp, ledf, df);
```

3. Performance Evaluation

Time per Cell (ms) vs Mesh Size

Execution time (ms) vs Implementation

Improved Roofline Model [4]

$$P = \frac{F/B}{\frac{1}{B_{peak}} + \frac{F/B}{F_{peak}}}$$

$(F_{peak}, B_{peak}) = (5.3TFLOPS, 732GB/sec)$

Schemes	F/B	GFlops
LBM	0.13	62.06
FDLBM (Lax-Wendroff) [template + coalesced]	0.20	111.68
FDLBM (Lax-Wendroff) [template + shared]	0.26	122.21
FDLBM (UTOPIA) [template + coalesced]	0.32	378.34
FDLBM (UTOPIA) [template + shared]	1.37	528.99

Peak Flops Tesla P100

Performance [GFlops] vs Arithmetic Intensity [FLOP/Byte]

Evaluation Environment

Architecture : ITO Subsystem B (R.I.I.T of Kyushu University), NVIDIA Tesla P100 (1,328-1,480 MHz), HBM2 : 732 GB/sec

Compiler : nvcc (CUDA v8.0.61), Performance Profiling Tool : Nvidia Profiler (v8.0.61), Optimize Option : -O3

4. Scientific Relevance

Flue instrument model (unit:mm)

$\nu = 1.5 \times 10^{-5} \text{ m}^2/\text{s}$
 $U_0 = 8 \sim 36 \text{ m/s}$
 $Cs = 346.18 \text{ m/s}$
 $\Delta t = 5.3 \mu\text{s}$

third-order upwind (UTOPIA)
second-order Runge-Kutta

Frequency distribution (14 m/s, 26 m/s)

Edge tone frequency calculated by Brown's equation [6]

$$f = 0.466j(100U - 40)\left(\frac{1}{h}\right) - 0.07$$

5. Conclusion and Future Work

Conclusion

- FDLBM is capable of achieving high effective performance on low B/F machines.
- FDLBM is able to reproduce the basic characteristics of the flue instrument.

Future Work

- Using high-order (nonlinear, compact) schemes and DRP schemes.
- Performance evaluation using the Cache-Aware Roofline model.

6. References

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